Python with Robots Mission 6 Lab Data Sheet – OBJ 5	Name:

Obj 5 – Line Follower Reflection
Essential Question: What limitations does the LineFollow1 program have? Test your line follower and answer the questions below.

What situations does this algorithm handle nicely?

What situations make it *fail*?

***Why* does it fail in those cases?**

Collected Data	
Line Position	**LEDs(vals)**
Far Left	
Center	
Far Right	